

$$1. I) \quad x_1(k+1) = y(k+1) = x_2(k) + 6u(k)$$

$$x_2(k+1) = y(k+2) - 6u(k+1) \stackrel{\uparrow}{=} y(k) = x_1(k)$$

dall'eq. i/o

$$y(k) = x_1(k)$$

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 6 \\ 0 \end{bmatrix} \quad C = [1 \quad 0] \quad D = 0$$

$$1. II) \quad Y_f(z) = z \cdot C(zI - A)^{-1} X(0) =$$

$$= z [1 \quad 0] \begin{bmatrix} z & -1 \\ -1 & z \end{bmatrix}^{-1} \begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} =$$

$$= z [1 \quad 0] \frac{\begin{bmatrix} z & 1 \\ 1 & z \end{bmatrix}}{z^2 - 1} \begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} = \frac{z^2 x_1(0) + z x_2(0)}{z^2 - 1}$$

Impongo $Y_f(z) = \delta \cdot \frac{z}{z-1}$

$$\frac{z^2 x_1(0) + z x_2(0)}{(z-1)(z+1)} = \delta \cdot \frac{z}{z-1} \Rightarrow \underline{x_1(0) = x_2(0) = \delta}$$

$$1. III) \quad u(k) = \delta(k) \Rightarrow U(z) = \frac{z}{z-1}$$

$$Y_f(z) = G(z) \cdot U(z)$$

$$G(z) = C(zI - A)^{-1} B + D =$$

$$= [1 \quad 0] \begin{bmatrix} z & -1 \\ -1 & z \end{bmatrix}^{-1} \begin{bmatrix} 6 \\ 0 \end{bmatrix} = \frac{6z}{z^2 - 1}$$

$$Y_f(z) = \frac{6z}{z^2 - 1} \cdot \frac{z}{z-1}$$

$$\frac{Y_f(z)}{z} = \frac{6z}{(z-1)^2(z+1)} = \frac{A}{z-1} + \frac{B}{(z-1)^2} + \frac{C}{z+1}$$

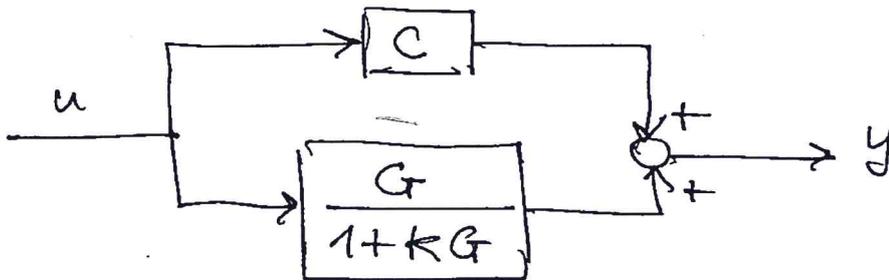
$$A(z^2-1) + B(z+1) + C(z-1)^2 = 6z$$

$$Az^2 - A + Bz + B + Cz^2 - 2Cz + C = 6z$$

$$\begin{cases} A+C=0 & A=-C & A=\frac{3}{2} \\ B-2C=6 & B=2C+6 & B=3 \\ -A+B+C=0 & C+2C+6+C=0 & C=-\frac{3}{2} \end{cases}$$

$$y_f(k) = \frac{3}{2} \mathbb{1}(k) + 3 \cdot k \cdot \mathbb{1}(k) - \frac{3}{2} (-1)^k \cdot \mathbb{1}(k)$$

2.I)



$$W(s) = C(s) + \frac{G(s)}{1+KG(s)} =$$

$$= \frac{1}{s+1} + \frac{\frac{1}{s(s+4)}}{1+k \frac{1}{s(s+4)}} =$$

$$= \frac{1}{s+1} + \frac{1}{s(s+4)+k} = \frac{1}{s+1} + \frac{1}{s^2+4s+k} =$$

$$= \frac{s^2+4s+k+s+1}{(s+1)(s^2+4s+k)} = \frac{s^2+5s+k+1}{(s+1)(s^2+4s+k)}$$

2.II) Modi convergenti $\Rightarrow k > 0$
 Modi aperiodici $\Rightarrow 4-k \geq 0$ } $\Rightarrow k \in (0, 4]$

Per $k=3$: $(s+1)(s^2+4s+3) = (s+1)^2(s+3)$

modi: e^{-t}, te^{-t}, e^{-3t}

2. III) Limite esiste finito $\Rightarrow k > 0$

$$\lim_{t \rightarrow +\infty} y_f(t) = G(0) = \frac{k+1}{k} > 4$$

$$k+1 > 4k \Rightarrow 3k < 1 \Rightarrow k \in (0, \frac{1}{3})$$

3. I) $x_1(k+1) = 0.6x_1(k) + 0.3x_3(k) + u(k)$

$$x_2(k+1) = 0.9x_2(k) + 0.4x_1(k)$$

$$x_3(k+1) = 0.7x_3(k) + 0.1x_2(k)$$

3. II) $y(k) = x_1(k)$

$$G(z) = C(zI - A)^{-1}B + D =$$

$$= [1 \ 0 \ 0] \begin{bmatrix} z-0.6 & 0 & -0.3 \\ -0.4 & z-0.9 & 0 \\ 0 & -0.1 & z-0.7 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} =$$

$$= \frac{(z-0.9)(z-0.7)}{(z-0.6)(z-0.9)(z-0.7) + 0.4(-0.1 \cdot 0.3)} =$$

$$= \frac{z^2 - 1.6z + 0.63}{(z-0.6)(z^2 - 1.6z + 0.63) - 0.012} =$$

$$= \frac{z^2 - 1.6z + 0.63}{z^3 - 2.2z^2 + 1.59z - 0.39}$$

i/o:

$$\begin{aligned} y(k+3) - 2.2y(k+2) + 1.59y(k+1) - 0.39y(k) &= \\ &= u(k+2) - 1.6u(k+1) + 0.63u(k) \end{aligned}$$

3. IV) Il sistema ha un polo in $z=1$!

$$\begin{array}{c|ccc|c} & 1 & -2.2 & 1.59 & -0.39 \\ 1 & & 1 & -1.2 & +0.39 \\ \hline & 1 & -1.2 & 0.39 & \emptyset \end{array}$$

$$G(z) = \frac{z^2 - 1.6z + 0.63}{(z-1)(z^2 - 1.2z + 0.39)}$$

le radici di questo polinomio sono interne al cerchio unitario

$$\lim_{k \rightarrow \infty} y_f(k) = \lim_{z \rightarrow 1} (z-1) \cdot Y_f(z) =$$

$$= \lim_{z \rightarrow 1} (z-1) \cdot G(z) \cdot 100$$

perché l'ingresso è $u(k) = 100 \delta(k) = \begin{cases} 100 & k=0 \\ 0 & k>0 \end{cases}$

$$= \lim_{z \rightarrow 1} \frac{z^2 - 1.6z + 0.63}{z^2 - 1.2z + 0.39} \cdot 100 =$$

$$= \frac{0.03}{0.19} \cdot 100 = \frac{3}{19} \cdot 100$$

$$4.I) \quad A = \begin{bmatrix} 0 & 1 \\ -5 & -1 \end{bmatrix}$$

$$\det(\lambda I - A) = \det \begin{pmatrix} \lambda & -1 \\ 5 & \lambda + 1 \end{pmatrix} = \lambda^2 + \lambda + 5$$

$$\lambda_{1,2} = \frac{-1 \pm \sqrt{-19}}{2} = -\frac{1}{2} \pm j \frac{\sqrt{19}}{2}$$

$$\text{Modi: } e^{-\frac{1}{2}t} \cos\left(\frac{\sqrt{19}}{2}t\right), \quad e^{-\frac{1}{2}t} \sin\left(\frac{\sqrt{19}}{2}t\right)$$

$$4.II) \quad G(s) = C(sI - A)^{-1}B + D =$$

$$= (1 \ 0) \begin{pmatrix} s & -1 \\ 5 & s+1 \end{pmatrix}^{-1} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \frac{(1 \ 0) \begin{pmatrix} s+1 & 1 \\ -5 & s \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}}{s^2 + s + 5} =$$

$$= \frac{s+2}{s^2 + s + 5}$$

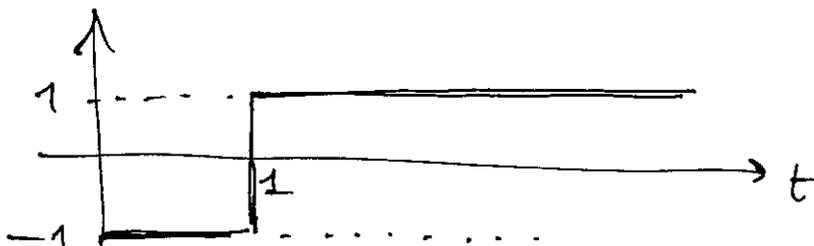
$$u(t) = 10 \cos(2t)$$

$$y_{\text{perm}}(t) = \underbrace{10 \cdot |G(j2)|}_{\text{Amplitude}} \cos(2t + \angle G(j2))$$

$$|G(j2)| = \left| \frac{j^2 + 2}{-4 + j^2 + 5} \right| = \left| \frac{j^2 + 2}{1 + j^2} \right| = \sqrt{\frac{8}{5}}$$

$$\text{Amplitude} = 10 \cdot \sqrt{\frac{8}{5}}$$

4.III)



$$u(t) = -\mathbb{1}(t) + 2 \cdot \mathbb{1}(t-1)$$

$$U(s) = -\frac{1}{s} + 2 \cdot \frac{1}{s} e^{-s}$$

$$Y_f(s) = G(s)U(s)$$

$$h(t) = \mathcal{L}^{-1}\left[G(s) \cdot \frac{1}{s}\right] = \mathcal{L}^{-1}\left[\frac{s+2}{s^2+s+5} \cdot \frac{1}{s}\right]$$

$$\Rightarrow y_f(t) = -h(t) + 2h(t-1) \cdot \mathbb{1}(t-1)$$

$$G(s) \frac{1}{s} = \frac{A}{s} + B \frac{s + \frac{1}{2}}{s^2 + s + 5} + C \frac{\frac{\sqrt{13}}{2}}{s^2 + s + 5}$$

$$A(s^2 + s + 5) + B(s + \frac{1}{2})s + C \frac{\sqrt{13}}{2}s = s + 2$$

$$A + B = 0$$

$$A + \frac{1}{2}B + \frac{\sqrt{13}}{2}C = 1$$

$$5A = 2$$

$$B = -\frac{2}{5}$$

$$C = \frac{2}{\sqrt{13}} \left(1 - \frac{2}{5} + \frac{1}{5}\right) = \frac{8}{5\sqrt{13}}$$

$$A = \frac{2}{5}$$

$$h(t) = \frac{2}{5} \cdot \mathbb{1}(t) - \frac{2}{5} e^{-\frac{1}{2}t} \cos\left(\frac{\sqrt{13}}{2}t\right) + \frac{8}{5\sqrt{13}} e^{-\frac{1}{2}t} \sin\left(\frac{\sqrt{13}}{2}t\right)$$